## TEMPERATURE CONTROLLER SERIES: PR-69



## 

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## CAUTION:

1. Always follow instructions stated in this product booklet.
2. Before installation, check to ensure that specifications agree with intended application.
3. Installation must be done by skilled technician.
4. Automation and controlled devices must be properly "installed" so that they are protected against any risk of involuntary actuations. 5. Suitable dampers should be provided in event of excessive vibrations.

## NOTE:

Models are indicated by special symbols as shown in table on Page 4 and given symbols are used while explaining the device functionality. Eg: coeF\# ${ }^{5,6,7,8,9,10,11,12}$ - Coefficient, Range: 0.1 to 10.0 default: 1

The example above explains that the feature is applicable only for 151F43B1,151G43B1,151H43B1,151J43B1, 151F43B, 151G43B, 151H43B, 151 J43B.
\#Symbols appear where description vary based on models. If the \# does not appear, then it indicates that the feature is applicable to all the models.

### 1.0 CATALOG DESCRIPTION:

| CAT ID | Action | Analog I/P | O/P 1 | O/P 2 | O/P 3 | Modbus | Symbol |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 151F42B | Single | YES | Relay | Relay | SSR | NA | \# 1 |
| 151G42B | Single | YES | Analog | Relay | SSR | NA | \#2 |
| 151H42B | Single | YES | Analog | Relay | Relay | NA | \#3 |
| 151 J42B | Single | YES | Relay | Relay | Relay | NA | \#4 |
| 151F43B1 | Dual | YES | Relay | Relay | SSR | YES | \#5 |
| 151G43B1 | Dual | YES | Analog | Relay | SSR | YES | \#6 |
| 151H43B1 | Dual | YES | Analog | Relay | Relay | YES | \#7 |
| 151 J43B1 | Dual | YES | Relay | Relay | Relay | YES | \#8 |
| 151F43B | Dual | YES | Relay | Relay | SSR | NA | \#9 |
| 151G43B | Dual | YES | Analog | Relay | SSR | NA | \#10 |
| 151H43B | Dual | YES | Analog | Relay | Relay | NA | \#11 |
| 151 J43B | Dual | YES | Relay | Relay | Relay | NA | \#12 |
| 151K42B | Single | YES | Relay | SSR | NA | NA | \#13 |
| 151L42B | Single | NO | Relay | Relay | SSR | NA | \#14 |

### 2.0 FEATURES:

> Field selectable thermocouple, RTD, 0-50 mV, 0-60 mV, 12-60 mV Voltage: 0-5V, 1-5V \& 0-10V Current: 4-20mA
> Auto tuning.
> Field configurable process and deviation alarms.
> Bump less Auto Manual transfer.
> Soft Start mode.
> Temperature range selection. $1 .{ }^{\circ} \mathrm{C}$ - Celsius 2. ${ }^{\circ} \mathrm{F}$ - Fahrenheit
> Dual display with configurable lower display. 1.Co-Controller Output 2.Effective Set Point 3.Set Point 4.Alarm threshold 5.Timer time 6.Unit
> Timer Functionality (Only for Single acting devices)
> Three outputs.
> Control modes: ON-OFF Symmetric, ON-OFF Asymmetric, Single acting PID control.
> Two set point storage.
> SSR driving with short circuit protection. Password "Enable" and "Disable" function added
> which helps user to enable the password as and when required. In Factory Default, Password is "Disabled".
> Additional Features available in dual acting devices: (Cat. Nos.: 151F43B1, 151G43B1, 151H43B1, 151J43B1,151F43B, 151G43B, 151H43B, 151J43B
-> Control modes: Neutral zone ON-OFF, ON-OFF Symmetric, ON-OFF Asymmetric, Dual acting PID control.
-> Additional two set point storage (Total Four Set point storage)
-> Rs485 Mod-bus communication. ( Not applicable for Cat ID:151 F43B, 151G43B, 151H43B, 151 J43B)
-> Ramp \& Soak Functionality

### 3.0 FRONT FASCIA:



## FRONT FASCIA DESCRIPTION:

1. PV : Displays the "Process Value".
2. SV : Displays the "Set Value".
3. Key'®' : Configurable key 'C'.
4. Key' ${ }^{\text {' }}$ ' : Scroll down key 'DN'.
5. Key'(4) : Scroll up key 'UP'.
6. Key' $($ ' : Enter key 'E'.
7. OP3 : LED indication for output 3.
8. OP2 : LED indication for output 2.
9. OP1 : LED indication for output 1.
10. '-' : Indicates that PV is less than(SP-Value in the setting LED).
11. ' $=$ ' : Indicates that PV is equal to SP.
12. ' + ' : Indicates that $P V$ is greater than(SP+Value in the setting LED).
13. 'AT' : This LED indicates the Auto tuning process is ON.
14. 'TM' : LED blinking- This indicates that timer process is ON.

LED Continuous ON- Timer time completed.

### 4.0 PRODUCT DESCRIPTION:

PR-69 is a single loop, single/dual acting Microprocessor based controller with ON-OFF, PID, and Auto tunning functionality. The product has two/four programmable set points and depending on model provides three different outputs.

Three Input sensor accepted in PR-69:

1. Thermocouples
2. RTD: PT-100 (Three wire compensation)
3. Standard mV signals:0-50 mV,0-60 mV, 12-60 mV.
4. Voltage $0-5 \mathrm{~V}, 1-5 \mathrm{~V}$ \& $0-10 \mathrm{~V}$, Current $4-20 \mathrm{~mA}$

### 5.0 DIMENSIONS (in mm):




BACK PLATE_WITH TERMINAL


BACK VIEW
Please refer pg. 83 to pg. 85 for connection diagrams.

### 6.0 TECHNICAL SPECIFICATIONS:

## Supply Voltage

110-240 VAC/DC, $-20 \%$ to $+10 \%, 50-60 \mathrm{~Hz}$

## Power Consumption

8 VA

## Temperature Sensors

Thermocouple J, K, E, S, B, R
RTD (PT100, 3 wire compensation),
mV signals ( $0-50 \mathrm{mV}, 0-60 \mathrm{mV}, 12-60 \mathrm{mV}$ )

## Analog I/P

Voltage 0-5V, 1-5V \& 0-10V
Current $4-20 \mathrm{~mA}$

## Measurement Range

Sensor J: 0 to $700^{\circ} \mathrm{C} / 32$ to $1292^{\circ} \mathrm{F}$
Sensor K: 0 to $1300^{\circ} \mathrm{C} / 32$ to $2372^{\circ} \mathrm{F}$
Sensor E: 0 to $600^{\circ} \mathrm{C} / 32$ to $1112^{\circ} \mathrm{F}$
Sensor S: 0 to $1750^{\circ} \mathrm{C} / 32$ to $3182^{\circ} \mathrm{F}$
Sensor B: 250 to $1820^{\circ} \mathrm{C} / 482$ to $3308^{\circ} \mathrm{F}$
Sensor PT100:-200 to $700^{\circ} \mathrm{C} /-328$ to $1292^{\circ} \mathrm{F}$
Sensor R: 0 to $1750^{\circ} \mathrm{C} / 32$ to $3182^{\circ} \mathrm{F}$

## Measurement Accuracy

$0.5 \%$ of full scale of $\mathrm{P}+100$, for $\mathrm{j}, \mathrm{K}+/-1 \%$ \& for other thermocouple it is $+/-3 \%$, For Tc and mV signals $+/-0.2 \%$ at $25^{\circ} \mathrm{C}$ (For DC Analog Input)

## Resolution

S, B, R: $1^{\circ} \mathrm{C}$
J, E, K, PT100: $0.1^{\circ} \mathrm{C}$ for Tc and mV signals $\mathrm{mV}: 0.001^{\circ} \mathrm{C}$

## Display

4- Digit 7 Segment LED Display with LED indicatation.

## Keypad

4-Keys: Configurable@, Down(DN), Up(UP), Enter(E).
Op1 rating \# $\#^{1,4,5,8,9,12}$ SPST, 5A, 250 VAC/30 VDC(RES.)
OP1 rating \# ${ }^{23,6,7,10,11} 4-20 \mathrm{~mA} / 0-10 \mathrm{VDC}$
Op1 rating $\#^{13,14}$ SPDT, 10A, 250VAC/30VDC (RES.)
Op2 rating SPST, 5 A at $240 \mathrm{VAC} / 3 \mathrm{~A}$ at 30 VDC
Op3 rating \# ${ }^{1,25,6,9,9,1,13,14}$ SSR Drive 12V, 24 mA DC max
Op3 rating $\#^{3,4,7,8,1,12}$ SPST,5 A,250VAC/30VDC (RES.)
Contact Material : AgNi
Life of relays:

| $\begin{aligned} & \text { of relays: } \\ & \text { OP1 \# } \#^{1,4,5,9,12} \end{aligned}$ | Mechanical life | $5 \times 10^{6}$ |
| :---: | :---: | :---: |
|  | Electrical life | : $1 \times 10^{5}$ |
| OP1 \# ${ }^{13,14}$ | Mechanical life | $: 1 \times 10^{7}$ |
|  | Electrical life | $: 1 \times 10^{5}$ |
| OP2 | Mechanical life | $: 5 \times 10^{6}$ |
|  | Electrical life | : $1 \times 10^{5}$ |
| OP3 \# ${ }^{3,4,7,8,1,12}$ | Mechanical life | $5 \times 10^{6}$ |
|  | Electrical life | $1 \times 10^{5}$ |

Max. Resistance in case of current output
(terminal 1 and 13 ) \# ${ }^{23,6,7,10,11} 600 \Omega$
Min. Resistance in case of voltage output
(terminals 11 and 12) \# ${ }^{2,3,6,7,10,11}$
$30 \mathrm{k} \boldsymbol{\Omega}$
Temperature Sampling Rate/PID Sampling Rate
$150 \mathrm{~ms} / \mathrm{s}$

## Weight (Unpacked)

280 g
Humidity
80\% Rh Non-condensing
Max. Operating Altitude
2000 m
Operating Temperature Range
$0^{\circ} \mathrm{C}$ to $50^{\circ} \mathrm{C}$

## Storage Temperature Range

$-20^{\circ} \mathrm{C}$ to $60^{\circ} \mathrm{C}$

## Pollution Degree

2
IP Protection
IP 40 for front panel and IP 20 for terminal and Housing

Dimensions (WXHXD)
$96 \times 96 \times 69.1$ (in mm)

## Mounting

Panel mounting

## Terminal Capacity

$2 \times 2.5 \mathrm{~mm}^{2}$
Torque
0.5 N.m (4.41b.in) to 0.7N.m (6.21b.in)

Certifications
CE, RoHS

### 7.0. EMC, SAFETY, ENVIRONMENTAL

## Product Standard

## IEC 61326

ESD
IEC 61000-4-2 Level II

## Radiated Susceptibility

IEC 61000-4-3 Level III
Electrical Fast Transients
IEC 61000-4-4 Level IV

## Surge

IEC 61000-4-5 Level IV

## Conducted Susceptibility

IEC 61000-4-6 Level III

## Conducted Susceptibility

IEC 61000-4-6 Level III
Voltage Dips and Interruptions
IEC 61000-4-11 (AC) All levels 1,2,4,5 (Criteria A) levels 3,6 (Criteria B)
IEC 61000-4-29 (DC) level 1 (Criteria A)
All levels 2,3,4,5 (Criteria B)

## Conducted Emission

CISPR 11 Class A

## Radiated Emission

CISPR 11 Class A

## Line Interruption

GTS3.3,Criteria "A" up to 20 ms , Criteria "B" up to 600 ms \& "C" above 600 ms

## Isolation Level :

## 151F42B / 151F43B

|  | Sensor | OP1 | OP2 | OP3 |
| :---: | :---: | :---: | :---: | :---: |
| Supply | 2 kV | 4 kV | 4 kV | 2 kV |
| Sensor | - | 4 kV | 4 kV | NA |
| OP1 | - | - | 4 kV | 4 kV |
| OP2 | - | - | - | 2 kV |

151G42B / 151G43B

|  | Sensor | OP1 | OP2 | OP3 |
| :---: | :---: | :---: | :---: | :---: |
| Supply | 2 kV | 2 kV | 4 kV | 2 kV |
| Sensor | - | NA | 4 kV | NA |
| OP1 | - | - | 2 kV | NA |
| OP2 | - | - | - | 2 kV |

151H42B/151H43B

|  | Sensor | OP1 | OP2 | OP3 |
| :---: | :---: | :---: | :---: | :---: |
| Supply | 2 kV | 2 kV | 4 kV | 4 kV |
| Sensor | - | NA | 4 kV | 4 kV |
| OP1 | - | - | 2 kV | 2 kV |
| OP2 | - | - | - | 4 kV |

151 J42B/151J43B

|  | Sensor | OP1 | OP2 | OP3 |
| :---: | :---: | :---: | :---: | :---: |
| Supply | 2 kV | 4 kV | 4 kV | 4 kV |
| Sensor | - | 4 kV | 4 kV | 4 kV |
| OP1 | - | - | 4 kV | 4 kV |
| OP2 | - | - | - | 4 kV |

## 151F43B1

|  | Sensor | OP1 | OP2 | OP3 | RS485 |
| :--- | :---: | :---: | :---: | :---: | :---: |
| Supply | 2 kV | 4 kV | 2 kV | 2 kV | 2 kV |
| Sensor | - | 4 kV | 2 kV | NA | NA |
| OP1 | - | - | 4 kV | 4 kV | 4 kV |
| OP2 | - | - | - | 2 kV | 4 kV |
| OP3 | - | - | - | - | NA |

151G43B1

|  | Sensor | OP1 | OP2 | OP3 | RS485 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Supply | 2 kV | 2 kV | 2 kV | 2 kV | 2 kV |
| Sensor | - | NA | 2 kV | NA | NA |
| OP1 | - | - | 2 kV | NA | NA |
| OP2 | - | - | - | 2 kV | 4 kV |
| OP3 | - | - | - | - | NA |

## 151H43B1

|  | Sensor | OP1 | OP2 | OP3 | RS485 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Supply | 2 kV | 2 kV | 4 kV | 4 kV | 2 kV |
| Sensor | - | NA | 2 kV | 2 kV | NA |
| OP1 | - | - | 2 kV | 2 kV | NA |
| OP2 | - | - | - | 2 kV | 2 kV |
| OP3 | - | - | - | - | 2 kV |

Note( $\#^{6,7}$ ): As there is no isolation between RS-485 and OP1, user must take care that the ground of circuits to which these outputs are connected should be isolated from each other.

## 151J43B1

|  | Sensor | OP1 | OP2 | OP3 | RS485 |
| :--- | :---: | :---: | :---: | :---: | :---: |
| Supply | 2 kV | 4 kV | 4 kV | 2 kV | 2 kV |
| Sensor | - | 4 kV | 2 kV | 2 kV | NA |
| OP1 | - | - | 4 kV | 4 kV | 4 kV |
| OP2 | - | - | - | 2 kV | 4 kV |
| OP3 | - | - | - | - | 2 kV |

151K42B

|  | Sensor | OP1 | OP2 |
| :---: | :---: | :---: | :---: |
| Supply | 2 kV | 4 kV | 2 kV |
| Sensor | - | 4 kV | NA |
| OP1 | - | - | 4 kV |

151F42B / 151F43B

|  | Sensor | OP1 | OP2 | OP3 |
| :---: | :---: | :---: | :---: | :---: |
| Supply | 2 kV | 2 kV | - | 2 kV |
| Sensor | - | 2 kV | - | - |
| OP1 | - | - | - | 2 kV |
| OP2 | - | - | - | - |

## Safety:

## Test Voltage between I/P and O/P

UL $508 \quad 2 \mathrm{kV}$
Impulse Voltage between Input and Output
IEC 60947-5-1 Level IV

## Single Fault

IEC 61010-1

## Insulation Resistance

UL $508>50 \mathrm{~K} \Omega$
Leakage Current
UL $508<3 \mathrm{~mA}$

## Environmental:

## Cold Heat

IEC 60068-2-1

## Dry Heat

IEC 60068-2-2

## Vibration

IEC 60068-2-6, 5 g

### 8.0 MEASUREMENT:

Parameters for this are included in the group "InP". Inputs accepted are Thermocouples ( $J, K, E, S, B, R), m$ signals ( $0-50 \mathrm{mV}$ ), ( $0-60 \mathrm{mV}$ ), ( $12-60 \mathrm{mV}$ ) , Current 4-20mA, Voltage 0-10V \& RTD PT100.For proper functionality, it is recommended to switch off and on the instrument, whenever these are modified. The parameters related to input are 'unit' - unit of measurement ( ${ }^{\circ} \mathrm{C},{ }^{\circ} \mathrm{F}$ ) and 'dP' - decimal point representation. In case of analog input, the input voltage gets divided over the range set in the parameters 'IScL' lower limit and 'ISch' upper limit. Instrument can be re-calibrated according to application needs, by using parameters "oFSt" and "rAtE". If "rAtE" $=1.000$, then using parameters "oFSt", it is possible to set positive or negative offset that is simply added to the value read by the probe.

If the offset is not constant for all the measurements, it is possible to operate the calibration on any of two points. In this case, in order to decide which values to program on parameters "oFSt" and "rAte",
the following formulae must be applied:
"rAte" $=(y 2-y 1) /(x 2-x 1)$
"oFSt" = y2 - rate*x2
Where,
$y \mathrm{l}=$ Measured temperature 1
$\mathrm{xl}=$ temperature displayed by instrument
y2 $=$ Measured temperature 2
x2 = temperature displayed by instrument
The instrument thus visualizes the temperature as:
$y=x *$ "rAtE" + "oFSt"
where $y=$ displayed value and $x=$ measured value

### 8.1 Output in case of measurement error:

In case of measurement error (over range/under range/sensor break), the instrument supplies the power as programmed on parameters
"oPP". In case of PID control, the power output is as a percentage of cycle time. In case of ON/OFF control, the Cycle time is automatically considered as 20s ("e.g. In event of probe error with ON/OFF control and "oPP $=50$ " the control output will be activated for 10 s and deactivated for 10 s till measurement error remains.)
If No Error

| Controller | Output Power |
| :---: | :---: |
| PID | As per \% of cycle time |
| On/Off | 20 Secs |
| If Error |  |
| Controller | Output Power |
| Any | As per programmed in opp |

### 9.0 DISPLAY:

Using parameters "dISP", located in the group "conF", it is possible to configure the lower display to visualize different parameters like the Control Output (coP), operating set point (SP). In group "conF", the parameters "LEd" is used to define the LED shift index functioning for the three LED's repesented as: ' $+{ }^{\prime},{ }^{\prime}-1$, ' $=$ '.
The lighting up of the ' $=$ ' LED indicates that the process value is within the range [SP-LEd] and [SP+LEd].
The lighting '-' LED indicates that the process value is lower than [SP-LEd] \& lighting up of ' + ' indicates that the process value is higher than [SP+LEd]

| Menu | Sub menu | Options |
| :---: | :---: | :---: |
| conF | dlsP | 1.coP |
|  |  | 2.SP |
|  |  | 3.EFSP |
|  |  | 4.A1th |
|  |  | 5.A2th |
|  |  | 6.Unit |
|  |  | 7.timr |

## Note:

1) If we select Unit-->C/F
i.e ( $\mathrm{C}:$ Celsius, $\mathrm{F}:$ Fahrenheit) then C or F will displays on lower display
2) If timr option is selected then set timer time will displayed on lower display

### 10.0 ACTIVE SET POINT SELECTION:

This instrument allows pre-programming of, up to 2 different set points ("SP1", "Sp2")..
(for \#1,\#2,\#3,\#4,\#13)

## OR

up to 4 different set points
("SP1", "SP2", "SP3", "SP4")
(for \#5,\#6,\#7,\#8,\#9,\#10,\#11,\#12)
and then selection of which one must be active.
The effective set point can be selected:
-by parameter "EFsP" in the group of parameters "SP"
-By key "C" if parameter "kEy" = "SPSL".
The maximum number of set points is determined by parameter " $n S P$ " located in the group of parameters "SP".
.......(for \#5,\#6,\#7,\#8,\#9,\#10,\#11,\#12)

### 10.0 ACTIVE SET POINT SELECTION:

The controller acts in three different ways:
1.Automatic Control
2.Control Off
3.Manual Control

| Menu | Sub menu | Options |
| :---: | :---: | :---: |
| conF | kEy | oPLP <br> oFF |

Note: The instrument switches into "Auto" state at the end of auto-tuning. When switched ON , it automatically assume its state at the last switch off.

### 11.1 Automatic Control (Auto):

Automatic control is the normal functioning state of the controller. When in Auto mode, the device will function as per parameter programmed on parameters cont.

### 11.2 Control OFF (OFF):

In this mode, all the COP(Controller) outputs are deactivated

### 11.3 Bumpless Manual/Open Loop Control(oPLP):

This options allows to manually program the power percentage given as output by the controller by deactivating automatic control. When the instrument is switched to manual control, the power percentage is same as last one supplied. To change the power output, adjust the parameter manual reset "rS" in the "rEg" group.

| Menu | Sub menu | Options |
| :---: | :---: | :---: |
| rEg | rS | Value |

### 12.1 ON/OFF Control:

All the parameters regarding ON/OFF control are listed in group "rEg". This type of control can be set by programming parameters "cont"= onFs for ON-OFF action with symmetric hysteresis OR onFA for ON-OFF action with asymmetrical hysteresis. It drives the output programmed as coP [selected by parameters. oPcF\# $\#^{5.6,7,9,9,10,11,12}$ in oP], depending on the measured temperature value, on effective set point, function mode ("FUnc") and on the hysteresis ("hESt"). The action can be explained as follows, In case of reverse action i.e. hEAt being set on parameters "FUnc" in "rEg" menu, the controller activates the output when the process value "PV" goes below [SP-hEST]. It deactivates the output when the PV goes above "SP+hEST"in case of symmetric ON-OFF control and above "SP" in case of Asymmetric ON-OFF control.

| Menu | Sub menu | Options |
| :---: | :---: | :---: |
| rEg | Func | hEAt |

## Symmetric On Off Control (hEAt):

| Condition | Action |
| :---: | :---: |
| $\mathrm{PV}<[\mathrm{SP}-\mathrm{hEST}]$ | Controller Output is activated |
| $\mathrm{PV}>[\mathrm{SP}+\mathrm{hEST}]$ | Controller Output is deactivated |

## Asymmetric On Off Control:

| Condition | Action |
| :---: | :---: |
| $\mathrm{PV}<[\mathrm{SP}-\mathrm{hEST}]$ | Controller Output is activated |
| $\mathrm{PV}>[\mathrm{SP}]$ | Controller Output is deactivated |

Similarly in case of direct action i.e.Cool being set on parameters. "Func", the controller activates the output when the process value "PV" goes above (SP+hEsT) and deactivates the output when "PV" goes below "SP-hEsT" in case of symmetric ON-OFF control and"SP" Asymmetric ON-OFF control.

DIRECT ACTING:

| Menu | Sub menu | Options |
| :---: | :---: | :---: |
| rEg | Func | cool |
| Symmetric On Off Control (cool): |  |  |
| Condition | Action |  |
| PV < [SP-hEST] | Controller Output is deactivated |  |
| PV $>[S P+h E S T]$ | Controller Output is activated |  |

Asymmetric On Off Control:

| Condition | Action |
| :--- | :---: |
| $\mathrm{PV}<[\mathrm{SP}-\mathrm{hEST}]$ | Controller Output is deactivated |
| $\mathrm{PV}>[\mathrm{SP}]$ | Controller Output is activated |






### 12.2 Neutral Zone ON/OFF Control (nr):

### 12.2.1 Action:

All the parameters referring to neutral zone ON/OFF control are listed in the group "rEg". This type of control can be set when two outputs, configured by parameter "oPcf" ("oPcF" = h1c2 configures OP1 as heater and OP2 as cooler) are programmed as "coP" and the parameters "cont" = nr. The neutral zone control is used to control processes in which there is an element which causes a positive increase in temperature (eg. Heater, Humidifier etc.) and an element which causes decrease in temperature (e.g. Cooler, de-humidifier, etc.) Depending on measurements of effective set point "SP" and on hysteresis "hESt", the control functions works on programmed outputs. The controller activates the output configured as heater when process value goes below [SP-hEst] and deactivates it once the PV reaches SP. Further it activates the output configured on cooler when process value goes above [SP+hESt]. The cooler output is deactivated when PV reaches SP again.

Note: This type of control is applicable for double acting cat ids only.

| Menu | Sub menu | Options |
| :---: | :---: | :---: |
| rEg | cont | nr |
| OP | oPcF | hlc2 |
| Condition | Heater | Cooler |
| $\mathrm{PV}<[\mathrm{SP}-\mathrm{hEST}]$ | ON | OFF |
| $\mathrm{PV}=\mathrm{SP}$ | OFF | OFF |
| $\mathrm{PV}>[\mathrm{SP}+\mathrm{hEST}]$ | OFF | ON |
| $\mathrm{PV}=\mathrm{SP}$ | OFF | OFF |



### 12.2.2 cdły Menu :

Compressor duty cycle "cdty" is used to protect compressor short cycling. It is a time based activation of the compressor. The activation of compressor can be avoided till the time set on parameter "cdty".
"thus" providing the delay. Time programmed on "cdty" is counted starting from last output deactivation and then even if the regulator requires to switch on the corresponding output, the activation is delayed till the time set on "cdty" elapses.

Note: This menu is visible only when control type is selected as nr (Neutral zone)

### 12.3 PID Control

### 12.3.0 Single Acting PID Control:

All the parameters referring to PID control are listed in the group "rEg". The single action PID control can be obtained by programming parameters. "cont" = Pld and works on output configured as "coP" Depending upon the effective setpoint "sP", function "FUnc" and on the instrument's PID algorithm the control output is calculated. The single action PID control algorithm foresees the setting following parameters:
"Pb" - Proportional Band.
"Int" - Integral Time
"dEr" - derivative time
"rS" - Manual Reset (if "Int=0" only)
for \# ${ }^{12,2,4,4,3,14: ~ " c t " ~-~ C y c l e ~ t i m e ~}$

| Menu | Sub menu | Options |
| :---: | :---: | :---: |
| rEg | cont | PID |
| OP | OP1/OP2/OP3 <br> (atleast one) | coP |
| rEg | FUnc | hEAt/cooL |

### 12.3.1 Double Acting PID Control ( $\left.\#^{5 ., 7,8,9,0,101,12}\right)$ :

All the parameters referring to PID control are listed in the group "rEg". The double action PID control is used to control processes where there is an element which causes a positive increase in temperature (ex. Heating) and an element which causes a decrease in temperature (cooling). This type of control is selected by setting "cont" as Pid setting. The outputs configured for HEAT or COOL action in oPcF menu should be configured as "coP" The effective set Point "SP" and the instruments algorithm decides the controller output of Double Action PID control.
The cycle times "hct"(Heat cycle time: for output acting on heater) and "cct" (cool cycle time: for output acting on cooler) should have low value with frequent intervention of control outputs, so that good stability of process variable can be achieved, in case of fast processes.

It is recommended to use solid state relays to drive actuators. The Double Action PID control algorithm needs the programming of following parameters:
"Pb" - Proportional Band
"Int" - Integral Time
"dEr" - derivative time
"hct" - Heat cycle time
"cct" - cool cycle time
"rS" - Manual Reset (if "Int=0 only)
"coEF" - Coefficient Relation between power heating and cooling element. Range between 0.1 to 10.
"coEF" > 1: represents that the cooling element is stronger than heating element.
"coEF" $=1$ : represents that the heating and cooling element are equally strong.
"coEF" < 1: represents that the heating element is stronger than cooling element.

| Menu | Sub menu | Options |
| :---: | :---: | :---: |
| rEg | cont | Pld |
| OP | oPcF | h1c2 |
| OP | OP1/OP2/OP3 <br> (atleast two) | coP |

### 13.0 AUTO TUNING:

Auto tuning is a process by which the controller automatically calculates the values of Pb , Int \& dEr suitable for the process. In this process, the controller carries out several operations on the process plant to determine these values.

1. Program and select desired Set Point.
2. Program parameters "cont"=PID.
3. For single action PID control, program parameters "Func" as "hEAt" if using heater or "cooL" if using cooler.
4. Also program the output to which the final control element is connected as "coP".
5. In case of Double action PID control, set "coP" on the two outputs selected using parameters "oPcF" to act on heater and cooler. Steps for Auto-tuning are as follows:

| Menu | Sub menu | Options |
| :---: | :---: | :---: |
| rEg | cont | Pld |
| OP | OP1/OP2/OP3 <br> (two for double acting) <br> OP1/OP2/OP3 <br> (one for single acting) | coP |
| rEg | Func(lf single acting) | hEAt/cooL |
| rEg | AUto | $1,2,3,4$ |

Note: Double acting device can be used as single acting device.
6. Program parameters. "Auto" as:
" 1 "- Tune at Every power ON. If auto-tuning is desired, each time the instrument is switched ON.
" 2 "- Tune at first power ON. If auto-tuning is desired, the next time the instrument is switched ON. Once the tuning is finished, the parameters. "Auto" is swapped automatically to "OFF".
" 3 "- Tune manually. If auto-tunning is to be started manually by pressing the config key programmed as"stAt"
" 4 "- Tune at every set point change or at the end of soft start. This activates auto-tuning at every change of set point or at the end of soft-startcycle.
7. Switch OFF the instrument power and then switch it ON to start tuning if "Auto" is set as " 1 " or " 2 " or by pressing config. key programmed as "stAt". Flashing LED AT indicates the activation of Auto-tunning function. To start the auto tune following condition needs to satisfy:
For Single Acting mode, if "Func" is "hEAt" OR For dual acting mode if first stage is heating. Conditions...
$P V<[S P-|S P / 5|]$ if soft start is configured OR
$P V<[S P-|S P / 3|]$ if soft start is not configured.
and $S P-P V>=10$
For Single acting mode, if "Func" is "cooL" or For Double acting mode if first stage is cooling.
Conditions:
$\mathrm{PV}>[\mathrm{SP}+[\mathrm{SP} / 5]]$ If Soft start is configured
OR
$\mathrm{PV}>[\mathrm{SP}+[\mathrm{SP} / 3]]$ If Soft start is not configured
and $P V-S P>=10$

For example on Auto tunning, refer page no. 88 If the above conditions are not satisfied at the start of auto tune, the display will show "ErAt" message and the instrument will take the control conditions according to previously programmed PID. To make 'ErAt' disappear, Press "ENTER" key. If autotune is not completed in 2 hours, the instrument shows 'NoAt' on display. The cycle in progress is automatically get stopped in case of sensor error. After correct PID parameters are tuned, the calculated values are stored in instrument memory.

### 14.0 RAMP AND SOAK \# ${ }^{5,6,7,8,9,10,111,12}$

1. The PR-69 has provision for three ramps and three soaks corresponding to SP1, SP2 and SP3.
2. All parameters related to Ramp-Soak functions are grouped in menu 'rEg'.
3. Three strategies have been adopted that determine the state of ramp and soak in case of power resumption after failure.

## Note:-

At the end of the Ramp \& Soak profile the controller switches 'OFF' controller outputs. To repeat the Ramp \& Soak profile reset the device. This can be done by assigning 'rSEt' to the configurable key in the 'ConF' menu. If the Ramp \& Soak profile is not desired, set all Ramp and soak parameters to 'InF' \& then reset the device.

### 14.1 Power Down Resumption Mode (Prmd):

a. cont: The device keeps in memory the last set value before the power failure. After resumption, it starts from the same value and continues the profile. In case of soak stage once the power is resumed, the stage continues for the remaining time.

| Power failure in | Action |
| :---: | :--- |
| Ramp stage | After power resumption, device will continue from <br> the last virtual sp value. <br> Assume 3 set points, SP1 $=50, ~ S P 2=80 ~ \& ~ S P 3 ~=~ 100 . ~$ <br> If the virtual set point is 65, and power failure occurs. <br> After power resumption, device will start from last <br> virtual set point with the respective ramp rate, <br> irrespective of the PV value. |


| Power failure in | Action |
| :---: | :--- |
| Soak stage | After resumption device will continue for remaining <br> soak time. <br> Eg: Assume 3 set points, Sp1 $=50, S P 2=80 \& S p 3=100$, <br> If the device is in second Soak Stage \& configured <br> soak time is 50 minutes. If power failure occurs after <br> 10 minutes, then after power resumption, device will <br> continue with soak stage of 40 minutes and move <br> towards the next SP with new ramp rate, irrespective <br> of the PV |

b. rbck: The device starts from present PV value and continues with the profile. In case of power failure in soak stage, once the power is resumed and if $P V$ is not equal to the target $S P$ of the given soak stage, then starting from PV the SP ramps up to the target SP value with the slope of previous ramp. Once target SP is reached, device move to soak stage which continues for the remaining time.

| Power failure in | Action |
| :---: | :--- |
| Ramp stage | $\mathrm{SP1=50C,SP2=60C,SP3=70C}$ <br> Ramp1 $=5 \mathrm{C} / \mathrm{min}$ <br> Ramp2=10C/min <br> Ramp3=15C/min <br> If device was in between 60C and 70C, if power <br> fails then after power resumption device will check <br> for PV. <br> If PV(40C) is less than current Ramping stage set <br> point i.e (SP2=60C) then device will start from 40C <br> with ramp rate of second stage(Ramp2=10C/min). |


| Power failure in | Action |
| :---: | :--- |
| Soak stage | Device will compare SP with PV if notequal then <br> device will ramp back from current PV with ramp <br> rate of last set point till the soak stage reached then <br> continue for remaining soaking period. <br> Eg: Assume three set points SP1=50,SP2=60,SP3=70 <br> If device was in between 60 and 70 if power fails <br> then after power resumption device will compare <br> PV with SP value. Consider PV is 40 which is not <br> equal to last set point SP which was 60 then device <br> will ramp back from 40 with ramp rate of second <br> stage and reach till 60. After reaching 60 device will <br> enter into soaking stage for remaining time. |

c. rsEt: On power failure, the entire ramp and soak profile is reset. At the end of the profile irrespective of 'Prmd ' the device switches OFF all the control outputs.

| Power failure in | Action |
| :--- | :--- |
| Ramp stage/ | Profile is reset and device will start from beginning. <br> Soak stage <br> Eg: Assume three set points $S P 1=50, S P 2=60, S P 3=70$ <br> If device was in between 60 and 70 if power fails <br> then after power resumption device will start form <br> 50 which is first set point irrespective of PV value in <br> both stages. |



### 14.2 Holdback (hbck):

### 14.2.0 Holdback In Ramp:

While in ramp mode if the difference between SP and PV value goes beyond Holdback value, the SP ramping stops and it is held on the given value as long as PV < (SP-hbck) (hEAt) OR PV >(SP+hbcK) (cool) range.

### 14.2.1 Holdback In Soak:

While in Soak mode if the difference between SP and PV value goes beyond Holdback value, the soak timing is stopped and it is resumed when PV comes back within (SP-hbck) (hEAt) and (SP+hbcK) (cool) range.

### 15.0 SOFT START:

All parameters referring to the soft start functioning are contained in the group "rEg". The soft start functioning allows limitation of output power when instrument is switched on for a limited period of time. Following parameters are needed:
"SSt" - Soft start time in hh: mm
"SSth" - Soft start threshold
"Stp" - Soft start power
Soft start functionality will abort when sst or ssth whichever earlier is met.

### 16.0 Timer:

1) When PV value reach or cross to SP then the Timer will start, during this process Opl=cop will be in controlling action.
2) Op2 \& Op3 can be assign to timer alarm.
3) Timer functionality will work in both PID \& ON-OFF mode.
for eg: When $P V$ reaches to $S P=100^{\circ} \mathrm{C}$ then the timer will start, Timer will be ON for 15 minutes then after completing timer time Opl will be continues OFF and if alarm is configure to timer then alarm will be ON as the timer time is elapsed.


## Note:

1) When ever the Set Timer time is competed then "OVER" message will display on lower display.

### 17.0 ALARMS:

1. Absolute low ("AbLO" on display): Alarm is activated if PV goes below Alth and is deactivated if PV goes above (Alth+AlhY).

| Menu | Sub menu | Options |
| :---: | :---: | :---: |
| AL1/AL2 | AltY | AbLo |


2. Absolute high ("Abhl" on display): Alarm is activated if PV goes above Alth and is deactivated if PV goes below (Alth-Alhy).

| Menu | Sub menu | Options |
| :---: | :---: | :---: |
| AL1/AL2 | AltY | Abhi |



## 3. Absolute band ("AbbA" on display):

Alarm is activated if PV goes above A1hi or below AlLo. It is deactivated if it goes below(Alhi-Alhy) or above (AlLo+Alhy).

| Menu | Sub menu | Options |
| :---: | :---: | :---: |
| AL1/AL2 | AltY | AbbA |


4. Deviation low ("dELo" on display): Alarm is activated if PV goes below (Effective Set Point(ESP) - Alth) and is deactivated when it goes above (Effective Set Point(ESP)-Alth + Alhy).

| Menu | Sub menu | Options |
| :---: | :---: | :---: |
| AL1/AL2 | AltY | dELo |


5. Deviation high("dEhi" on display): Alarm is activated when PV goes above Effective Set Point(ESP)+A1th) and is deactivated When it goes below (Effective Set Point(ESP)+Alth-Al hy).

| Menu | Sub menu | Options |
| :---: | :---: | :---: |
| AL1/AL2 | AltY | dEhi |


6. Deviation band ("dEbA" on display): Alarm is activated when PV goes above(Effective Set Point (ESP)+Alhi) or below(Effective Set Point(ESP) - A1Lo) and is Deactivated when PV goes below (Effective Set Point(ESP) + Alhi - Alhy) or above (Effective Set Point(ESP) - AlLo + Alhy).

| Menu | Sub menu | Options |
| :---: | :---: | :---: |
| AL1/AL2 | AltY | dEbA |


7. Output low("OPLO" on display): Alarm is activated if output goes below olLV and deactivated when output goes above (olLV+olhs).

| Menu | Sub menu | Options |
| :---: | :---: | :---: |
| AL1/AL2 | AltY | oPLo |


8. Output high("OPhi" on display): Alarm is activated if output goes above olhv and deactivated when output goes below (olhv-olhs).

| Menu | Sub menu | Options |
| :---: | :---: | :---: |
| AL1/AL2 | AltY | oPhl |



## ALARM FUNCTIONALITY

| Menu | Sub Menu | Options | Details | Dependencies | Functions |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\begin{aligned} & \mathrm{AL1} \\ & \mathrm{OR} \\ & \mathrm{AL2} \end{aligned}$ | Alty | AblO | Absolute Low <br> Activation: PV < Alth <br> Deactivation: PV > Alth+AlhY | PV,Alth,AlhY | To alert user when PV falls below predefined value.(Alth) |
|  |  | Abhl | Absolute High <br> Activation: $\mathrm{PV}>\mathrm{Alth}$ <br> Deactivation: PV < Alth - AlhY | PV, Alth, AlhY | To alert user when PV exceeds predefined value. (Alth). |
|  |  | AbbA | Absolute band <br> Activation: $\mathrm{PV}>\mathrm{A}$ lhi or $\mathrm{PV}<\mathrm{AlLo}$ <br> Deactivation: PV < Alhi-A1hY or PV > A1Lo+AlhY | PV, Alhi, AlLo, AlhY | To alert user when PV, 1.falls below predefined value.(A1Lo) <br> OR <br> 2.exceeds predefined value.(Alhi). |
|  |  | dELo | Deviation Low <br> Activation: $\mathrm{PV}<(S P-A 1$ th $)$ <br> Deactivation: PV > (SP - Alth)+AlhY | PV, SP, Alth, AlhY | To alert user when PV falls below the SP by the value set in Alth |
|  |  | dEhl | Deviation High <br> Activation: $\mathrm{PV}>(\mathrm{SP}+\mathrm{A} 1$ th $)$ <br> Deactivation: $\mathrm{PV}<(S P+A 1$ th $)$-Alh $Y$ | PV, SP, Alth, AlhY | To alert user when PV exceeds the SP by the value set in Alth. |
|  |  | dEbA | Deviation Band <br> Activation: PV < (SP-AlLo) or PV > (SP+Alhi) Deactivation: PV > (SP - AlLo) + AlhY or $P V<(S P+A l t h)-A 1 h Y$ | PV, SP, Allo, Alhi, AlhY | To alert user when, 1.PV falls below the SP by the value set in A1Lo. <br> 2. PV exceeds the SP by the value set in Alhi. |
|  |  | oPLo | Output Low <br> Activation: COP < olLV <br> Deactivation: COP > olLV + olhs | COP,ollV,01hS | To alert user when COP falls below value set in olLV. |
|  |  | oPhl | Output High <br> Activation: COP > olhV <br> Deactivation: COP < olhV + olhs | COP,olhV,01hS | To alert user when COP exceeds value set in olhV. |


| Menu | Sub menu | Options |
| :---: | :---: | :---: |
| AL1/AL2 | AltY | AbLo |
|  |  | Abhl |
|  |  | AbbA |
|  |  | dELo |
|  |  | dEhl |
|  |  | dEbA |
|  |  | oPLo |
|  |  | oPhl |

### 17.2 Alarm Functions:

| Sr | Value | $\quad$ Details | Application |
| :---: | :---: | :--- | :--- |
| 1 | 0 | Normal <br> Activation: When alarm condition occurs. <br> Deactivation: When the alarm condition disappears. | Normal |
| 2 | 1 | Acknowledged <br> Activation: When alarm condition occurs. <br> Deactivation: 1. When the alarm condition disappears. <br> 2. When Configurable key programmed for alarm acknowledgment and press in alarm <br> condition. | To ignore the alarm condition |
| 3 | 2 | Delayed <br> Activation: delayed by time set in AldL parameter after occurrence of the alarm condition. <br> Deactivation: When the alarm condition disappears. <br> Note: During the delay if the alarm condition disappears, alarm will not be generated. | To delay the alarm generation, <br> some times alarm can be <br> generated for shorter time due to <br> some disturbance in system. |
| 4 | 4 | Latched <br> Activation: When alarm condition occurs. <br> Deactivation: When Configurable key programmed for alarm acknowledgment and press <br> once alarm generated. <br> Note: Alarm will not get automatically deactivated once generated. | To record or draw attention of <br> alarm generation condition every <br> time. Since no automatic of alarm. |
| 5 | 8 | No alarm at Power On <br> Activation: If alarm condition exist at power on, alarm will not be activated. Once device <br> goes in no alarm condition after power on, there after alarm will be activated at every <br> occurrence of the alarm condition. <br> Deactivation: Alarm will be deactivated In no alarm condition. | To avoid alarm after power on. <br> Since possibility of alarm condition <br> after every power on. |
| 6 | 16 | No alarm at SP change <br> Activation: If alarm condition generates after SP change, alarm will not be activated. <br> Once device goes in no alarm condition after SP change, there after alarm will be activated <br> at every occurrence of the alarm condition. <br> Deactivation: Alarm will be deactivated in no alarm condition. | To avoid alarm after change in $S P$. <br> Since possibility of alarm condition <br> after every time change in SP. |

### 17.2 Alarm Functions:

| Sr | Value | Details | Application |
| :---: | :--- | :--- | :--- |
| 7 | $24=$ |  |  |
| $16+8$ | No alarm at SP change + No alarm at Power On <br> Activation: If alarm condition exist at power on or If alarm condition generates after SP <br> change, alarm will not be activated. Once device goes in no alarm condition after SP <br> change or power on, there after alarm will be activated at every occurrence of the alarm <br> condition. <br> Deactivation: Alarm will be deactivated in no alarm condition. | Note: We can club the different <br> alarm functionality by doing the <br> addition of the set value for those <br> alarm functions. |  |

## Note:

Alarm types and functions are explained for alarm

1. The explanation is same for alarm
2. Binary addition of alarm function allows Combination of different function.

Eg. If it is required to have no alarm at power On [8] and no alarm at sP change [16], set function as 24.

### 18.0 PROGRAMMING:

Follow given procedure to program the device:

1. Press key 'E' to enter menus. If password "Enabled", then 'PV' display shows "codE", which is blinking and 'SV' display shows " 0 ".
2. Enter code as "69" using 'UP' key. Press key 'E' to enter into menu. If wrong code is entered, then the device exits from programming mode. If correct code is entered, the device enters into the set of menus.
3. Using 'UP' or 'DN' key we can move to desired set of parameter.
4. Press key ' $E$ ', to enter the group of parameters related to the main menu. Here, the 'PV' display shows the menu and 'SV' shows the value programmed on it.
5. To change this value, press key 'E'. Using 'UP' or 'DN' key, select the value to be entered. Press key 'E' to confirm the value or key 'C' to maintain the previous value.
6. Whenever the value of the menu is being edited, the 'PV' display blinks. Here, 'UP' and 'DN' key change the value on 'SV' display. When the display is not blinking, we can move to next menu using 'UP' or 'DN' key. To exit from the menu press key 'C'
7. Key 'C' acts as "EXIT" key when in programming mode. While on main screen, when 'PV' display shows temperature and 'SV' display shows user configured value, it performs the function as configured on it in the "key" parameter of "conF" menu.

### 19.0 SEVEN SEGMENT DISPLAY:

| A | B | C | D | E | F | G | H | 1 | J | K | L | M |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| A | $\square$ | [ | $\square$ | E | F | 9 | h | i | L | $\hbar$ | L | - |
| N | $\bigcirc$ | P | Q | R | S | T | U | v | W | X | Y | Z |
| $\square$ | $\square$ | $P$ | 9 | $r$ | 5 | t | U | $\square$ | ! | 三 | 4 | - |

20.0 MENUS: MAIN MENU: SP (Set point)

| Parameter |  | Description |
| :---: | :---: | :---: |
| 1 | SPLL | Set point low level Range: - 1999 to set point active, default: -1999 |
| 2 | SPhL | Set point high level <br> Range: Set point active to 9999, default: 9999 |
| 3 | $\begin{aligned} & \mathrm{nSP} \#^{5.6,7,8 .} \\ & \#^{9,10,11,12 .} \end{aligned}$ | No. of. Set point Range: 1 to 4, default: 4 |
| 4 | EFSP | Effective Set point. <br> Range\# ${ }^{5,6,7,8,910,111,12}: 1$ to nsP, Range\# ${ }^{1,23,4,13,14}: 1$ to 2 default: 1 |
| 5 | SP1 | Set point 1 <br> Range: sPLL to sPhL, default: 0 |
| 6 | SP2 | Set point 2. Range: sPLL to sPhL, default: 0 |
| 7 | $\begin{aligned} & \text { Sp3 } \#^{5,6,7,8} \\ & \#^{9,10,11,12} \end{aligned}$ | Set Point 3 <br> Range: sPLL to sPhL, default: 0 |
| 8 | $\begin{aligned} & \text { Sp4 } \#^{5,6,7,8} \\ & \#^{9,10,11,12} \end{aligned}$ | Set Point 4 Range: sPLL to sPhL, default: 0 |

## MAIN MENU: InP(Input)

| 1 | SEnS | Sensor: <br> Range: <br> J : J Thermocouple <br> K : K Thermocouple <br> Ptl : PT100 RTD <br> E : E Thermocouple <br> S: S Thermocouple <br> B : B Thermocouple <br> R: R Thermocouple <br> Analog Input: <br> 0-10 : Voltage Analog Sensor <br> 0-5 : Voltage Analog Sensor <br> 1-5 : Voltage Analog Sensor <br> 4-20 : Current Analog Sensor <br> 1260: 12 to 60 mV <br> 0_50: 0 to 50 mV <br> 0_60: 0 to 60 mV <br> default: J Thermocouple <br> Note: For \# ${ }^{14}$ <br> Sens: R,S,K, J,PT100 are accepted. |
| :---: | :---: | :---: |
| 2 | IScL | Low scale in case of analog inputs Range: -1999 to Isch, default: 0 |
| 3 | Isch | High scale in case of analog inputs Range: IscL to 9999, default: 100 |
| 4 | rAtE | Slope of straight line <br> Range: 0.001 to 2.000 , default: 1.000 |
| 5 | oFSt | Offset of straight line Range: -1999 to 9999, default: 0 |
| 6 | oPP | Output power in case of error <br> Range: 0 to 100.0\% \# ${ }^{1,2,3,4,13,14}$ <br> Range: $-100.0 \%$ to $100.0 \% \#^{5.6,7,9,9,10,11,12}$ <br> default: 0 |
| 7 | dP | Decimal point Range: $S / B / R / K$ thermocouple:0 J/E thermocouple \& Pt 100:0 to 1, Analog Signals: 0 to 3 , default: 0 |
| 8 | UnIt | Temperature measurement unit Range: $\mathrm{C}^{\circ}$ or $\mathrm{F}^{\circ}$, default: $\mathrm{C}^{\circ}$ |
| 9 | $\begin{aligned} & \text { rFSh } \\ & \#^{23,6,7,10,11} \end{aligned}$ | Analog signal output update rate Range: 150 to 5000 ms , default: 150 ms |
| 10 | PvLo <br> $\#^{2,3,6,7,10,11}$ | Process variable low <br> Range: - 1999 to 9999, <br> corresponds to $4 \mathrm{~mA} / 0 \mathrm{~V}$, default:0 |
| 11 | Pvhl <br> $\#^{2,3,6,7,10,11}$ | Process variable High Range: -1999 to 9999 Corresponds to $20 \mathrm{~mA} / 10 \mathrm{~V}$, default: 100 |
| 12 | $\begin{aligned} & \text { coLo } \\ & \#^{2,3,6,7,10,11} \end{aligned}$ | Controller output low <br> Range: 0 to $100 \#^{2.3},-100$ to $100 \#^{6,7,10,11}$ Corresponds to $4 \mathrm{~mA} / 0 \mathrm{~V}$, default: 0 |
| 13 | $\begin{aligned} & \text { cohl } \\ & \#^{2,3,6,7,10,11} \end{aligned}$ | Controller output high <br> Range: 0 to $100 \#^{2,3},-100$ to $100 \#^{6,7,10,11}$ <br> Corresponds to $20 \mathrm{~mA} / 10 \mathrm{~V}$, default:10.0 |
| 14 | Filt | Filter menu <br> Range: 0 to 10, default: 2 |


| MAIN MENU: oP(output) |  |  |
| :---: | :---: | :---: |
| Parameter |  | Description |
| 1 |  | Output configure as: Range: <br> 1.h2c3: heat 2 Cool 3 , <br> 2.h3c2: heat 3 Cool 2. default: h2c3 |
| 1 | $\begin{array}{\|c\|c\|} \hline O P C F \\ \#^{58,12} \end{array}$ | Output Configure as: Range: <br> 1. hlc2: heat 1 Cool 2 <br> 2. hlc3: heat 1 Cool 3 <br> 3. h2c3: heat 2 Cool 3 <br> 4. h2cl: heat 2 Cool 1 <br> 5. h3cl: heat 3 Cool 1 <br> 6. h3c2: heat 3 Cool 2, default: h1c2 |
| 2 | $\begin{aligned} & \text { O1cF } \\ & \#^{23,67.0 .10,11} \end{aligned}$ | Output 1 configured as: Range: <br> 1. IOP: 4-20 mA output <br> 2. V OP: $0-10 \mathrm{~V}$ output, default: I OP |
| 3 | OPI $\#^{23}$ | Output 1 to act as: Range: <br> 1. coP: Controller output <br> 2.tEmP: temperature re-transmitted output, default: temP |
| 3 | $\begin{aligned} & \text { OP1 } \\ & \#^{6,710,11} \end{aligned}$ | Output 1 to act as: Range: <br> 1. coP: Controller output <br> 2. tEmP: Temperature re-transmitted output <br> 3. EsP: Effective Set Point, default: tEmP |
| 3 |  | Output 1 to act as: <br> Range: <br> 1. coP: Controller output <br> 2. Alno: Alarm 1 normally open <br> 3. Alnc: Alarm 1 normally closed <br> 4. A2no: Alarm 2 normally open <br> 5. A2nc: Alarm 2 normally closed <br> 6. SEnb: Sensor break <br> 7. BrkL: Loop break alarm <br> 8. OFF: Relay off, default: cop |
| 4 | OP2 | Output 2 to act as: <br> Range: <br> 1. coP: Controller output <br> 2. Alno: Alarm 1 normally open <br> 3. Alnc: Alarm 1 normally closed <br> 4. A2no: Alarm 2 normally open <br> 5. A2nc: Alarm 2 normally closed <br> 6. Senb: Sensor break <br> 7. BrkL: Loop break alarm <br> 8. oFF: Relay off <br> 9. trAL\# ${ }^{1,4,1,3,4}$ : Timer Alarm, default: off |
| 5 | OP3 | Applicable for all cat ids except \#13. (Same Functionality as Op2, Only trAL: Timer Alarm is applicable for cat_id \# ${ }^{1,23,4,4}$ ) |
| 6 |  | Loop break output Lbol $\#^{58,12}$ : Output 1 Lbo2 : Output 2 Lbo3 : Output 3 default : Lbo2 |
| 7 | brkt | Break loop time Range: Off to 9999 s , default: off |
| 8 |  | Timer time Range: Off to 9999 Min, default: ofF |
|  | $\begin{aligned} & \operatorname{trAt} \\ & \#^{1,23,4,13} \end{aligned}$ | Timer Alarm time Range: On to 9999 Min, default: On |

## MAIN MENU: ALI (Alarml)

|  | rameter | Description |
| :---: | :---: | :---: |
| 1 | Alty | Alarm 1 type: <br> Range: <br> 1. AbLo: Absolute low <br> 2. Abhl: Absolute high <br> 3. AbbA: Absolute band <br> 4. dELo: Deviation Iow <br> 5. dEhl: Deviation High <br> 6. dEbA: Deviation band <br> 7. oPLo: Output low <br> 8. oPhl: Output High, default: AbLo |


| Parameter |  | Description |
| :---: | :---: | :---: |
| 2 | AlFn | Alarm 1 function: <br> 0: Alarm on error <br> +1: Acknowledge alarm <br> +2: Delayed alarm <br> +4: Latch alarm <br> +8 : No alarm at power on <br> +16: No alarm at set-point change <br> Range: 0-31, default: 0 |
| 3 | Allo | Alarm 1 low level Range: -1999 to A1th, default: -1999 |
| 4 | Alth | Alarm 1 Threshold <br> Range: Allo to AlHi, default: 0 |
| 5 | Alhl | Alarm 1 high level Range: Alth to 9999, default:9999 |
| 6 | AlhY | Alarm 1 hysteresis <br> Range: OFF to 9999, default: 1 |
| 7 | O1LV | $\begin{aligned} & \text { Output } 1 \text { low value } \\ & \text { Range \# } \#^{1,2,3,4,13}: 0.0 \% \text { to } 01 \mathrm{HV} \\ & \text { Range } \#^{5.6,7,9,10,11,12}:-100.0 \% \text { to olHV, default: } 0.0 \\ & \hline \end{aligned}$ |
| 8 | OlhV | Output 1 high value <br> Range: olLV to 100.0 \%, default: 100.0 |
| 9 | olhs | Output 1 hysteresis <br> Range: OFF to 100.0 \%, default:1 |
| 10 | AldL | Alarm 1 delay <br> Range: OFF to 9999 s, default: Off |

Menus for Alarm 2 are same as for Alarm 1.

## MAIN MENU: REG(Regulator)

| Parameter |  | Description |
| :---: | :---: | :---: |
| 1 | cont | Controller type: <br> Range: <br> 1. onFS: On-Off Symmetric, <br> 2. onFA: On-Off Asymmetric <br> 3. PID: PID controller <br> 4. nr: neutral zone On-OFF( $\left.\#^{5.6,7,8,9,10,11,12}\right)$ default: PID |
| 2 | FUnc | Controller type: <br> Range: <br> 1. hEAt: Reverse acting <br> 2. cool: Direct acting, default: hEAt |
| 3 | hEst | Hysteresis for On-Off controller Range: OFF - 9999, default:1 |
| 4 | AUto | Auto tuning: <br> Range: <br> oFF: auto tuning off <br> 1: auto tuning at every power on <br> 2: auto tuning at first power on <br> 3: Start manually <br> 4: auto tune at every set point change, default: 2 |
| 5 | Pb | Proportional band Range: 0 to 9999, default: 10 |
| 6 | Int | Integral time Range: OFF to 9999 s, default: 120 |
| 7 | dEr | Derivative time Range: OFF to 9999 s, default: 30 |
| 8 | $\begin{aligned} & c \dagger \\ & \#^{1.2,3,4,13} \end{aligned}$ | Cycle time Range:1 to 130 s, default: 20 |
| 9 | $\begin{aligned} & \text { rs } \\ & \#^{1,2,3,4,13} \end{aligned}$ | Manual reset <br> Range: 0 to 100.0 \%, default: 0 |
| 9 | $\mathrm{rs} \#^{5,6,7,8}$ $\#^{9,10,11,12}$ | Manual reset <br> Range: -100.0 to 100.0 \%, default: 0 |
| 10 | $\begin{aligned} & \hline \text { hct } \#^{5,6,7,8} \\ & \#^{9,10,11,12} \end{aligned}$ | heat cycle time Range: 1 to 130 s, default: 10 |
| 11 | $\begin{aligned} & \hline \operatorname{ct+}{ }^{5,6,7,8} \\ & \#^{4,10,11,12} \end{aligned}$ | Cool cycle time, Range: 1 to 130 s, default: 10 |
| 12 | coeF $\#^{5.6,7.8}$ $\#^{9,10,11,12}$ | Coefficient, Range: 0.1 to 10.0, default: 0.1 |
| 13 |  | Compressor duty cycle Range: O(Off) to 9999 s , default: 0 |


|  | rameter | Description |
| :---: | :---: | :---: |
| 14 | Prmd \# ${ }^{5,6,7,8}$ $\#^{9,10,11,12}$ | Power down mode Range: <br> 1. cont: Continue <br> 2. rbck: Ramp back <br> 3. rsEt: Reset, default: cont |
| 15 | $\begin{aligned} & \text { rmP1 } \\ & \#^{55,7,8} \\ & \#^{19,1,1,1,12} \end{aligned}$ | Ramp 1 <br> Range: 0.00 to 99.99 - Inf unit/min, default: Inf |
| 16 | $\begin{aligned} & \text { Sok } \\ & { }^{\$_{0.7 .8}^{8}} \\ & { }^{10,1,1,1,12} \end{aligned}$ | Soak 1 <br> Range: 0.00 to 99.59 - Inf hh:mm, default: Inf |
| 17 | $\begin{aligned} & r m P 2 \\ & \#^{5 \cdot, 7.8} \\ & \#^{1,10,1,1,12} \end{aligned}$ | Ramp 2 <br> Range: 0.00 to 99.99 - Inf unit/min, default: Inf |
| 18 | $\begin{aligned} & \text { Sok2 } \\ & { }^{50,7,8} \\ & \#^{5,1,1,1,1,12} \end{aligned}$ | Soak 2 <br> Range: 0.00 to 99.59 - Inf hh:mm, default: Inf |
| 19 | $\begin{aligned} & \text { rmP3 } \\ & \#^{5 \cdot, 7,8} \\ & \#^{5,1,1,1,1,12} \end{aligned}$ | Ramp 3 <br> Range: 0.00 to 99.99- Inf unit/min, default: Inf |
| 20 | $\begin{aligned} & \text { Sok3 } \\ & \$^{5,7,7,1} \\ & \#^{9,0,0,1,12} \end{aligned}$ | Soak 3 <br> Range: 0.00 to 99.59 - Inf hh:mm, default: Inf |
| 21 | hbck $\#^{5,6,7}$ \# ${ }^{9.10 .11,12}$ | Ramp hold back <br> Range: OFF to 9999, default: OFF |
| 22 | $\begin{aligned} & \text { SSP } \\ & \#_{1,3,4}^{12,4} \\ & \#^{13,14} \end{aligned}$ | Soft start power <br> Range: 0.0 to 100.0, default: 0 |
| 22 | $\begin{aligned} & \text { SSP } \#^{5.677} \\ & \#^{9.1011,12} \end{aligned}$ | Soft start power <br> Range: - 100.0 to 100.0, default: 0 |
| 23 | SSt | Soft start time <br> Range: 0.00 (OFF) to 7.59 (hh:mm), default: Off |
| 24 | SSth | Soft start threshold <br> Range: -1999 to 9999, default: 0 |


| Parameter | Description |
| :---: | :--- |
| rSEt | To reset device and load default setting. Please press the <br> enter key. <br> If "Yes" - will display message to confirm reset. <br> If "No" - will get back to menu. <br> Affer Confirm, |
| If "Yes "- Reset device and back to main screen. |  |
| If "No" - Back to main screen. |  |

## Main Menu: modb (Modbus)\# ${ }^{5}$

| 1 | Addr | Device Id <br> Range: 1 to 99, default: 1 |
| :--- | :--- | :--- |
| 2 | bAUd | Baud rate: <br> Range: <br> 1. 3: 300 baud rate <br> 2. 6: 600 baud rate <br> 3. 12: 1200 baud rate <br> 4. 24: 2400 baud rate <br> 5. 48: 4800 baud rate <br> 6. 96: 9600 baud rate <br> 7. 192: 19200 baud rate, default: 96 |
| 3 | PArt | Parity: <br> Range: <br> 1. EvEn: Even parity <br> 2. odd: odd parity <br> 3. None: None parity default: None |
| 4 | bItS | No. of bits <br> Range: 8 to 9, default: 8 |
| 5 | StPb | No. of stop bits <br> Range: 1 to 2, default: 1 |

### 21.0 MODBUS :

PR-69 has adopted widely used MODBUS RTU protocol. The MODBUS RTU communication functions implemented in PR-69 series are: Function 3 - Read Holding Variables (read); Function 6 - Preset Single Register (write); Function 16 - Preset Multiple Register (write).

These functions allow the supervisory program to read and modify any data of the controller.

The communication is based on messages sent by the master station (host) to the slave stations (PR-69) and vice versa. Every a message contains four fields:
a) Slave address (from 1 to 99)
b) Function code: contains 3, 6 or 16 for specified functions.
c) Information field: contains data like word addresses and word values as required by function in use.
d) Control word: a cyclic redundancy check (CRC) performed with particular rules for CRC.

Note: For function 16 - Preset Multiple Register, We can only write one parameter at a time.

### 3.1 Function 3 - Read n Word

The request has the following frame:

| Filed Name | Byte Position |
| :--- | :---: |
| Slave MODBUS ID | Byte 0 |
| Function Code(3) | Byte 1 |
| First word Address MSB | Byte 2 |
| First word Address LSB | Byte 3 |
| Number of words MSB | Byte 4 |
| Number of wordsLSB | Byte 5 |
| CRC MSB | Byte 6 |
| CRC LSB | Byte 7 |

The normal reply(as opposed to exception reply)has the following frame:

| Filed Name | Byte Position |
| :--- | :---: |
| Slave MODBUS ID | Byte 0 |
| Function Code(3) | Byte 1 |
| NB Number of Read bytes | Byte 2 |
| Value of first word MSB | Byte 3 |
| Value of first word LSB | Byte 4 |
| Following Words | Byte 5 |
| CRC Error Check MSB | Byte NB+2 |
| CRC Error Check LSB | Byte NB+3 |

3.2 Function 6 - One word write. The request has the following frame:

| Filed Name | Byte Position |
| :--- | :---: |
| Slave MODBUS ID | Byte 0 |
| Function Code(6) | Byte 1 |
| Word Address MSB | Byte 2 |
| Word Address LSB | Byte 3 |
| Value of first word MSB | Byte 4 |
| Value of first word LSB | Byte 5 |
| CRC Error Check MSB | Byte 6 |
| CRC Error Check LSB | Byte 7 |

### 3.3 The exception reply

An exception reply is given when the request is formally correct, but cannot be satisfied standing particular situations; the reply contains a code indicating the cause of the missing regular reply. The frame is:

| Filed Name | Byte Position |
| :--- | :---: |
| Slave MODBUS ID | Byte 0 |
| Function Code(3) | Byte 1 |
| First Word Address MSB | Byte 2 |
| First Word Address LSB | Byte 3 |
| Number of Word MSB | Byte 4 |
| Number of Word LSB | Byte 5 |
| CRC Error Check LSB | Byte 6 |
| CRC Error Check MSB | Byte 7 |

3.4 Function 16 - Preset Multiple Register, one word write.

The request has the following frame:

| Filed Name | Byte Position |
| :--- | :---: |
| Slave MODBUS ID | Byte 0 |
| Function Code(0X10) | Byte 1 |
| Start register no,(high byte) | Byte 2 |
| Start register no,(Low byte) | Byte 3 |
| No. of register to write(High byte) | Byte 4 |
| No. of register to write(Low byte) | Byte 5 |
| No. of data bytes | Byte 6 |
| Data 0 MSB | Byte 7 |
| Data 0 LSB | Byte 8 |
| Data 1 MSB | Byte 9 |
| Data 1 LSB | Byte 10 |
| Data 2 MSB | Byte 11 |
| Data 2 LSB | Byte 12 |
| CRC bytes of 1 to 6 (LSB) | Byte 13 |
| CRC bytes of 1 to 6 (MSB) | Byte 14 |

Note: Number Of data bytes that follows 3 registers X 2 Bytes each = 6

The normal reply(as opposed to exception reply) has the following frame:

| Filed Name | Byte Position |
| :--- | :---: |
| Slave MODBUS ID | Byte 0 |
| Function Code(0X10) | Byte 1 |
| Start register no,(high byte) | Byte 2 |
| Start register no,(Low byte) | Byte 3 |
| No. of register written(High byte) | Byte 4 |
| No. of register written(Low byte) | Byte 5 |
| CRC bytes of 1 to 6 (LSB) | Byte 6 |
| CRC bytes of 1 to 6 (MSB) | Byte 7 |

1) Illegal Function code-1
2) Illegal data address-2
3) Illegal data value field-3
4) Slave device busy-6

Address 0 used for broadcasting messages has not been implemented in Pr69.

## 22. MODBUS QUERIES:

## 1. Variable - Pv

Description: Process Variable
Data type: Signed short
Range: -1999 to 9999
Decimal dependence: dP
READ/WRITE: Read
Address (in HEX) : 1001

## 2. Variable - coP

Description: Control Output
Data type: Signed short
Range: - 100 to 100
Decimal dependence: 0
READ/WRITE: Read
Address (in HEX): 1002

## 3. Variable - AL1

Description: Alarm 1 Status
Data type: Unsigned short
Range: OFF-xxxx xxx0, ON- $x x x x x x x 1$
Decimal dependence: NA
READ/WRITE: Read
Address (in HEX): 1003
4. Variable - AL2

Description: Alarm 2 Status
Data type: Unsigned short
Range: OFF-xxxx xx0x, ON- xxxx xxlx
Decimal dependence: NA
READ/WRITE: Read
Address (in HEX): 1003

## 5. Variable - sEnb

Description: Sensor break alarm status
Data type: Unsigned short
Range: OFF-xxxx x0xx, ON- xxxx xlxx
Decimal dependence: NA
READ/WRITE: Read
Address (in HEX): 1003

## 6. Variable - LbA

Description: Loop break alarm status
Data type: Unsigned short
Range: OFF-xxxx 0xxx, ON- xxxx 1xxx
Decimal dependence: NA
READ/WRITE: Read
Address (in HEX): 1003

## 7. Variable - SP

Description: Effective set point
Data type: Signed short
Range: sPLL to sPHL
Decimal dependence: dP
READ/WRITE: Read
Address (in HEX): 1004

## 8. Variable - stAt

Description: Regulator status
Data type: Unsigned short
Range: OFF - 0, Manual - 1,
AUTO SYM ON/OFF-2, AUTO ASYM ON/OFF-3,
AUTO N ZONE ON/OFF-4,
AUTO PID TUNE ON-5, AUTO PID TUNE OFF-6
READ/WRITE: Read
Decimal dependence: NA, Address (in HEX): 1005

## 9. Variable - MvEr

Description: Model Version
Data type: Unsigned short
Range: 105:Pr05, 106:PR06, 107: Pr07, 108: PR08
Decimal dependence: NA
READ/WRITE: Read
Address (in HEX): 1006

## 10. Variable - cvEr

Description: Code Version
Data type: Unsigned short
Decimal dependence: NA
READ/WRITE: Read
Address (in HEX): 1007

## 11. Variable - rFLg

Description: Ramp Soak Flg status
Data type: Unsigned short
Range:
NO RAMP SOAK ON: 0
RAMP1 STAGE: 1
SOAK 1 STAGE: 2
RAMP2 STAGE: 3
SOAK2 STAGE: 4
RAMP3 STAGE: 5
SOAK3 STAGE: 6
RAMP SOAK END: 7
Decimal dependence: NA
READ/WRITE: Read, Address (in HEX): 1008

## 12. Variable - Aout\# ${ }^{6,8}$

Description: Value Transmitted on Analog output
Data type: Unsigned short
Range: 3 to 21 or 0-10
Decimal dependence: NA
READ/WRITE: Read, Address (in HEX): 1009
13. Variable - Output 1 status (ON/OFF) $\#^{5,6,7,8}$

Description :This is for indication of OP 1
Data type: Unsigned short
Range: 0: OFF, 1:ON
Decimal dependence: NA
READ/WRITE: Read, Address (in HEX): 1009
14. Variable - Output 2 status (ON/OFF) \# ${ }^{5,6,7,8}$

Description: This is for indication of OP2
Data type: Unsigned short
Range: 0: OFF - 1 : ON
Decimal dependence: NA
READ/WRITE: Read, Address (in HEX): 100A
15. Variable - Output 3 status (ON/OFF) ${ }^{5.6,7,8}$

Description: This is for indication of OP3
Data type: Unsigned short
Range:0: OFF - 1 : ON
Decimal dependence: NA
READ/WRITE: Read, Address (in HEX): 100B

## 16. Variable - Status OF PV w.r.t SP\# ${ }^{5.6,7,8}$

Description: This is for relation between PV \& SP
Data type: Unsigned short
Range: 0-3
In case of sensor break: 0
"-" (PV<SP): 1
" $=$ " ( $\mathrm{PV}=\mathrm{SP}$ ): 2
"+" (PV>SP):3
Decimal dependence: NA
READ/WRITE: Read, Address (in HEX): 100C

## SP

## 1. Variable - SPLL

Description: Set point low
Data type: Signed short
Range: -1999 to setpoint as selected by EFSP
Decimal dependence: dP
READ/WRITE: Read/Write
Address (in HEX): 2001

## 2. Variable - SPhL

Description: Set point high
Data type: Signed short
Range: Setpoint as selected by EFsP to 9999
Decimal dependence: dP
READ/WRITE: Read/Write, Address (in HEX): 2002

## 3. Variable - nSP

Description: Number of set point
Data type: Unsigned short
Range: 1 to 4
Decimal dependence: NA
READ/WRITE: Read/Write, Address (in HEX): 2003

## 4. Variable - EFSP

Description: Effective set point
Data type: Unsigned short
Range: 1 to $n s P$
Decimal dependence: NA
READ/WRITE: Read/Write
Decimal dependence: dP, Address (in HEX): 2004

## 5. Variable - SP1

Description: Set point 1
Data type: Signed short
Range: spLL to sphL
Decimal dependence: dP
READ/WRITE: Read/Write, Address (in HEX): 2005

## 6. Variable - SP2

Description: Set point 2
Data type: Signed short
Range: spLL to sphL
Decimal dependence: dP
READ/WRITE: Read/Write, Address (in HEX): 2006

## 7. Variable - SP3

Description: Set point 3
Data type: Signed short
Range: spLL to sphL
Decimal dependence: dP
READ/WRITE: Read/Write, Address (in HEX): 2007

## 8. Variable - SP4

Description: Set point 4
Data type: Signed short
Range: spLL to spHL,
Decimal dependence: dP,
READ/WRITE: Read/Write, Address (in HEX): 2008

## InP

1. Variable - SEns

Description: Sensor select
Data type: Unsigned short
Range:
$0=\mathrm{J}$ thermocouple, 1 = K thermocouple, 2 = E thermocouple
$3=S$ thermocouple, $4=B$ thermocouple, $5=$ P+100 RTD
$6=0-50 \mathrm{mV}$ signal, $7=0-60 \mathrm{mV}$ signal, $8=12-60 \mathrm{mV}$,
$9=R$ thermocouple, $10=4-20 \mathrm{~mA}, 11=0-10 \mathrm{~V}, 12=0-5 \mathrm{~V}, 13=1-5 \mathrm{~V}$
Decimal dependence: NA
READ/WRITE: Read/Write, Address (in HEX): 2009

## 2. Variable - IScL

Description: Analog input low
Data type: Signed short
Range: -1999 to Isch
Decimal dependence: dP
READ/WRITE: Read/Write, Address (in HEX): 200A

## 3. Variable - ISch

Description: Analog input high
Data type: Signed short
Range: IscL to 9999
Decimal dependence: dP
READ/WRITE: Read/Write
Address (in HEX): 200B

## 4. Variable - rAtE

Description: Measurment Rate
Data type: Signed short
Range: 0.001 to 2.000
Decimal dependence: 3
READ/WRITE: Read/Write
Address (in HEX): 200C

## 5. Variable - oFSt

Description: Measurement Offset
Data type: Signed short
Range: - 1999 to 9999
Decimal dependence: dP
READ/WRITE: Read/Write
Address (in HEX) : 200D

## 6. Variable - oPP

Description: Output power in case of error
Data type: Signed short
Range: -100.0 to 100.0
Decimal dependence: 1
READ/WRITE: Read/Write, Address (in HEX): 200E

## 7. Variable - dP

Description: Decimal point
Data type: Unsigned short
Range: 0 to 3
Decimal dependence: 0
READ/WRITE: Read/Write
Address (in HEX) : 200F

## 8. Variable - unlt

Description: Unit of measurement
Data type: Unsigned short
Range: 0- ${ }^{\circ} \mathrm{C}$, 1 - ${ }^{\circ} \mathrm{F}$
Decimal dependence: NA
READ/WRITE: Read/Write, Address (in HEX): 2010

## 9. Variable - rFSh\# ${ }^{6,7}$

Description: Update pace of analog output
Data type: Unsigned short
Range: 150 to 5000
Decimal dependence: NA
READ/WRITE: Read/Write
Address (in HEX): 2011

## 10. Variable - PvLo\# ${ }^{6,7}$

Description: Process value/Set point low value for analog output according to value defined on OP1.
Data type: Signed short
Range: - 1999 to Pvhi
Decimal dependence: dP, READ/WRITE: Read/Write
Address (in HEX): 2012

## 11. Variable - Pvhi\#\#, ${ }^{6,7}$

Description: Process value/Set point high value for analog output according to value defined on OP1
Data type: Signed short
Range: PvLo to 9999
Decimal dependence: dP
READ/WRITE: Read/Write
Address (in HEX): 2013

## 12. Variable - CoLo\# ${ }^{6,7}$

Description: Control output low value
Data type: Signed short
Range: - 100.0 to Cohl
Decimal dependence: 1
READ/WRITE: Read/Write, Address (in HEX): 2014

## 13. Variable - Cohi\# ${ }^{6,7}$

Description: Control output high value
Data type: Signed short
Range: CoLo to 100.0
Decimal dependence: 1
READ/WRITE: Read/Write
Address (in HEX): 2015

## oP

## 1. Variable - oPcF\# ${ }^{5.8}$

Description: Output Configure
Data type: Unsigned short
Range: 0: H1C2, 1: H1C3, 2: H2C1, 3: H3C1,
4: H2C3, 5: H3C2
Decimal dependence: NA
READ/WRITE: Read/Write, Address (in HEX): 2016

## 1. Variable - oPcF\# ${ }^{6,7}$

Description: Output Configure
Data type: Unsigned short
Range: 0: H2C3, 1: H3C2
Decimal dependence: NA
READ/WRITE: Read/Write, Address (in HEX): 2016

## 2. Variable - olcF\# ${ }^{6,7}$

Description: Output 1 Config
Data type: Unsigned short
Range: 0: I_oP, 1: V_oP
Decimal dependence: NA
READ/WRITE: Read/Write, Address (in HEX): 2017

## 3. Variable - oP $1 \#^{6,7}$

Description: Outputl act on
Data type: Unsigned short
Range: 0: coP, 1: temp, 2:esp
Decimal dependence: NA
READ/WRITE: Read/Write, Address (in HEX): 2018

## 4. Variable - oP $1 \#^{5,8}$

Description: Outputl act on
Data type: Unsigned short
Range: 0: coP, 1: Alno, 2: Alnc, 3: A2no, 4: A2nc,
5: sEnb, 6: BrkL, 7: Off
Decimal dependence: NA
READ/WRITE: Read/Write, Address (in HEX): 2018

## 5. Variable - oP2

Description: Output 2 act on
Data type: Unsigned short
Range: 0: coP, 1: Alno, 2: Alnc, 3: A2no,4: A2nc
5: sEnb, 6: BrkL, 7: Off
Decimal dependence: NA
READ/WRITE: Read/Write, Address (in HEX): 2019

## 6. Variable - oP3

Description: Output 3 act on
Data type: Unsigned short
Range: 0: coP, 1: Alno, 2: Alnc, 3: A2no, 4: A2nc
5: sEnb, 6: BrkL, 7: Off
Decimal dependence: NA
READ/WRITE: Read/Write, Address (in HEX): 201A

## 7. Variable - LboP

Description: Loop break alarm act on
Data type: Unsigned short
Range: 0: Lbo $1 \#^{58 .}$ 1: Lbo2, 2: Lbo3, $0=\mathrm{Lb}$ 2, 1: Lbo3\# ${ }^{6,7}$
Decimal dependence: NA
READ/WRITE: Write, Address (in HEX): 201B

## 8. Variable - brkt

Description: Loop Break time
Data type: Unsigned short
Range: 0 to 9999
Decimal dependence: NA
READ/WRITE: Read/Write, Address (in HEX): 201C

## Alarms Types

1. Variable - A1tY

Description: Alarm 1 type
Data type: Unsigned short
Range: 0: AbLo, 1 : AbHI, 2: AbbA, 3: dELo, 4: dEHI,
5: dEbA, 6: oPLo, 7: oPHI
Decimal dependence: NA
READ/WRITE: Read/Write, Address (in HEX): 201D

## 2. Variable - Alfn

Description: Alarm 1 Function
Data type: Unsigned short
Range: 0 to 31
Decimal dependence: 0
READ/WRITE: Read/Write, Address (in HEX): 201E

## 3. Variable - AlLo

Description: Alarm 1 Function
Data type: Signed short
Range: -1999 to Alth
Decimal dependence: dP
READ/WRITE: Read/Write, Address (in HEX): 201F

## 4. Variable - A1th

Description: Alarm 1 Function
Data type: Signed short
Range: Allo to Alhi
Decimal dependence: dP
READ/WRITE: Read/Write, Address (in HEX): 2020

## 5. Variable - Alhi

Description: Alarm 1 High
Data type: Signed short
Range: Alth to 9999
Decimal dependence: dP
READ/WRITE: Read/Write, Address (in HEX): 2021

## 6. Variable - A1hY

Description: Alarm 1 hysteresis
Data type: Unsigned short
Range: 0 to 9999
Decimal dependence: dP
READ/WRITE: Read/Write, Address (in HEX): 2022

## 7. Variable - ollv

Description: Output Low alarm1 value
Data type: Signed short
Range: - 100.0 to ol HV
Decimal dependence: 1
READ/WRITE: Read/Write, Address (in HEX): 2023

## 8. Variable - olhv

Description: Output high alarm1 value
Data type: Signed short
Range: olLV to 100.0
Decimal dependence: 1
READ/WRITE: Read/Write, Address (in HEX): 2024

## 9. Variable - olhs

Description: Output alarm hysterisis 1
Data type: Unsigned short
Range: OFF to 100.0
Decimal dependence: 1
READ/WRITE: Read/Write, Address (in HEX): 2025

## 10. Variable - A1dL

Description: Alarm 1 delay
Data type: Unsigned short
Range: OFF to 9999
Decimal dependence: 0
READ/WRITE: Read/Write, Address (in HEX): 2026

## Al2

## 1. Variable - A2tY

Description: Alarm 2 type
Data type: Unsigned short
Range: 0: AbLo, 1: AbHi, 2: AbbA, 3: dELo
4: dEHi, 5: dEbA, 6: oPLo, 7: oPHi
Decimal dependence: NA
READ/WRITE: Read/Write, Address (in HEX): 2027

## 2. Variable - A2Fn

Description: Alarm 2 Function
Data type: Unsigned short
Range: 0 to 31
Decimal dependence: 0
READ/WRITE: Read/Write, Address (in HEX): 2028

## 3. Variable - A2Lo

Description: Alarm 2 Function
Data type: Signed short
Range: - 1999 to A2th
Decimal dependence: dP
READ/WRITE: Read/Write, Address (in HEX): 2029

## 4. Variable - A2Th

Description: Alarm 2 Function
Data type: Signed short
Range: A2Lo to A2hi
Decimal dependence: dP
READ/WRITE: Read/Write, Address (in HEX): 202A

## 5. Variable - A2hl

Description: Alarm 2 High
Data type: Signed short
Range: A2th to 9999
Decimal dependence: dP
READ/WRITE: Read/Write, Address (in HEX): 202B

## 6. Variable - A2hY

Description: Alarm 2 hysteresis
Data type: Unsigned short
Range :0 to 9999
Decimal dependence: dP
READ/WRITE: Read/Write, Address (in HEX): 202C

## 7. Variable - o2Lv

Description: Output Low alarm 2 value
Data type: Signed short
Range: - 100.0 to 02Hv
Decimal dependence: 1
READ/WRITE: Read/Write, Address (in HEX): 202D

## 8. Variable - o2hv

Description: Output high alarm 2 value
Data type: Signed short
Range: o2LV to 100.0
Decimal dependence: 1
READ/WRITE: Read/Write, Address (in HEX): 202E

## 9. Variable - o2hs

Description: Output alarm hysteresis 2
Data type: Unsigned short
Range: OFF to 100.0
Decimal dependence: 1
READ/WRITE: Read/Write,Address (in HEX): 202F

## 10. Variable - A2dL

Description: Alarm 2 delay
Data type: Unsigned short
Range: OFF to 9999
Decimal dependence: 0
READ/WRITE: Read/Write, Address (in HEX): 2030

## 1. Variable - Cont

Description: Control type
Data type: Unsigned short
Range: 0: onFS, 1: onFA, 2: Pid, 3: nr
Decimal dependence: NA
READ/WRITE: Read/Write, Address (in HEX): 2031

## 2. Variable - Func

Description: Control action functioning
Data type: Unsigned short
Range: 0: HEAt, 1 : cool
Decimal dependence: NA
READ/WRITE: Read/Write, Address (in HEX): 2032

## 3. Variable - hESt

Description: On Off Hysterisis
Data type: Unsigned short
Range: 0 to 9999
Decimal dependence: NA
READ/WRITE: Read/Write, Address (in HEX): 2033

## 4. Variable - AUto

Description: Autotune
Data type: Unsigned short
Range: 0: Off, 1: 1, 2: 2, 3: 3, 4: 4
Decimal dependence: NA
READ/WRITE: Read/Write, Address (in HEX): 2034
5. Variable - Pb

Description: Proportional Band
Data type: Unsigned short
Range: 0 to 9999
Decimal dependence: 0
READ/WRITE: Read/Write, Address (in HEX): 2035

## 6. Variable - Int

Description: Integral time
Data type: Unsigned short
Range: 0 to 9999
Decimal dependence: 0
READ/WRITE: Read/Write, Address (in HEX): 2036

## 7. Variable - dEr

Description: Derivative time
Data type: Unsigned short
Range: 0 to 9999
Decimal dependence: 0
READ/WRITE: Read/Write, Address (in HEX): 2037

## 8. Variable - rs

Description: Manual rese $\dagger$
Data type: Signed short
Range: -100 to 100
Decimal dependence: 1
READ/WRITE: Read/Write, Address (in HEX): 2038

## 9. Variable - hct

Description: Heater output cycle time
Data type: Unsigned short
Range: 1 to 130
Decimal dependence: 0
READ/WRITE: Read/Write, Address (in HEX): 2039

## 10. Variable - cct

Description: Cooler output cycle time
Data type: Unsigned short
Range: 1 to 130
Decimal dependence: 0
READ/WRITE: Read/Write, Address (in HEX): 203A

## 11. Variable - coEF

Description: Coefficient
Data type: Unsigned short
Range: 0.1 to 10.0
Decimal dependence: 1
READ/WRITE: Read/Write, Address (in HEX): 203B

## 12. Variable - cdty

Description: Compressor On delay time
Data type: Signed short
Range: 0 to 9999
Decimal dependence: 0
READ/WRITE: Read/Write, Address (in HEX): 203C

## 13. Variable - Prmd

Description: Power down resume mode
Data type: Unsigned short
Range: 0: Cont, 1: rbcK, 2: rSEt
Decimal dependence: NA
READ/WRITE: Read/Write, Address (in HEX): 203D

## 14. Variable - rmP1

Description: Ramp 1
Data type: Unsigned short
Range: 0 to 99.99
Decimal dependence: 2
READ/WRITE: Read/Write, Address (in HEX): 203E

## 15. Variable - rmP2

Description: Ramp 2
Data type: Unsigned short
Range: 0 to 99.99
Decimal dependence: 2
READ/WRITE: Read/Write, Address (in HEX): 203F

## 16. Variable - rmP3

Description: Ramp 3
Data type: Unsigned short
Range: 0 to 99.99
Decimal dependence: 2
READ/WRITE: Read/Write, Address (in HEX): 2040
17. Variable - soK1

Description: Soak 1
Data type: Unsigned short
Range: 0 to 99.59 (hour:min)
Decimal dependence: 2
READ/WRITE: Read/Write, Address (in HEX): 2041

## 18. Variable - soK2

Description: Soak 2
Data type: Unsigned short
Range: 0 to 99.59 (hour:min)
Decimal dependence: 2
READ/WRITE: Read/Write, Address (in HEX): 2042
19. Variable - soK3

Description: Soak 3
Data type: Unsigned short
Range: 0 to 99.59 (hour:min)
Decimal dependence: 2
READ/WRITE: Read/Write, Address (in HEX): 2043

## 20. Variable - hbck

Description: Ramp Hold back
Data type: Unsigned short
Range: 0 to 9999
Decimal dependence: dP
READ/WRITE: Read/Write, Address (in HEX): 2044

## 21. Variable - SSP

Description: Soft start Power
Data type: Unsigned short
Range: -100 to 100
Decimal dependence: 1
READ/WRITE: Read/Write, Address (in HEX): 2045

## 22. Variable - SST

Description: Soft start time
Data type: Unsigned short
Range: 0 to 7:59 (hh:mm)
Decimal dependence: 2
READ/WRITE: Read/Write, Address (in HEX): 2046

## 23. Variable - SSTH

Description: Soft start threshold
Data type: Signed short
Range: -1999 to 9999
Decimal dependence: dp
READ/WRITE: Read/Write, Address (in HEX): 2047

## Conf

## 1. Variable - Key

Description: Configure Key
Data type: Unsigned short
Range: 0: StAt, 1: oPLP, 2: Ack, 3: oFF,
4: SPSL, 5: ChSP, 6: rSEt, 7: noFc
Decimal dependence: NA
READ/WRITE: Read/Write, Address (in HEX): 2048
2. Variable - diSP

Description: Configure Display
Data type: Unsigned short
Range: 0: sP, 1:Co, 2:A1th, 3:A2th, 4:EFSP
Decimal dependence: NA
READ/WRITE: Read/Write, Address (in HEX): 2049

## 3. Variable - Led

Description: Led Compare Index
Data type: Unsigned short
Range: 0 to 9999
Decimal dependence: dP
READ/WRITE: Read/Write, Address (in HEX): 204A

## 23. CONNECTION DIAGRAMS:

## 151F42B / 151F43B



## 151G42B / 151G43B



## 151H42B/151H43B



## 151J42B / 151J43B



## 151F43B1

| 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  |  |  |  |  |  |
|  |  | $\Gamma^{0,2} 2$ |  |  |  |  | ${ }^{N}{ }^{\mathrm{L}}$ |  |  |
| 11 | 12 | 13 | 14 | 15 | 16 | 17 | 18 | 19 | 20 |

## 151G43B1



## 151H43B1



151J43B1


## 151K42B



151L42B


## 24. FAQs:

1. How to change effective set point selection using key ' $C$ '?
A. "SLSP" (select effective set point) must be programmed on "kEy" parameter in the "conf" menu. If 'C' key is pressed and held for 2 sec while on main screen "EFsP" is displayed on the upper display and currently effective set point ( 1 if sP 1 is effective and 2 if $s P 2$ is effective) is displayed on the lower display. The upper display starts blinking. Using 'UP' /'DN' key the value can be changed. Press 'E' to activate the set point.Upper display stps blinking. Press 'C' key to exit from menu to main screen.

| Menu | Sub menu | Options |
| :---: | :---: | :---: |
| conf | kEy | $\mathrm{C}^{\prime}$ |

## 2. What is 'rAtE' and 'oFst' parameter in the 'InP' menu?'

A. If it is required to apply slope and/or offset to the temperature measured by the instrument, it can be done by using the above parameters. Any value set on above a parameter allows the device to see temperature as below:
Display temp. $=$ rAtE* Measured Temp + oFst This helps to re-calibrate the instrument.

## 3. What is "Sens" Break alarm and break loop alarm?

A. To select sensor break alarm set "sEnb" on the desired output. Whenever sensor break error occurs, the corresponding relay is set. To select break loop alarm, break loop alarm time i.e. "Brkt " is to be set. If the controller output remains at $100 \%$ for the above time, then loop break alarm is given. If any relay output is set for the alarm, the given relay is switched on. Break loop alarm works only in PID mode. Break loop alarm can be turned off by moving the controller to OFF mode and then back to auto mode by pressing properly programmed 'C' key.

| Menu | Sub menu | Options |
| :---: | :---: | :---: |
| OP | OP1 / OP2 | sEnb |
| OP | brkt | value |

Note : Break loop alarm works only in PID mode.

## 4. What is Soft start threshold and Soft start time?

A. Soft start time is the time for which the soft power is provided after On. Soft start threshold is the absolute temperature upto which soft power is provided. While in soft start, if any of the above value is reached, the soft start ends.

| Menu | Sub menu | Options |
| :---: | :---: | :---: |
| rEG | Auto | $1,2,3,4$ |

## 5. How to start Auto tuning?

A. Depending on the value programmed on the parameter "Auto" in "rEg" group auto tuning can be started.
1: Auto tuning is started at every power ON of the instrument.
2: Auto tuning is started at first power ON of the instrument.
3: Auto tuning can be started manually by the user by pressing properly programmed 'C' key.
4: Auto tuning is started at every set point change.
The set point changed should be the effective point.
Even if the value on parameter "EFSP" in the "SP" menu is changed and the values parameter "SP1" and "SP2" in the menu are different, the auto tuning is started. Following condition must be satisfied to start auto tune:
Controller should be in PID mode.
If Soft start is configured and auto tune is on 1 or 2 or 4:
"sP" be set the on $\mathrm{PV}<(S P-|S P / 5|)$ for HEAT action.
or $P V>(S P+|S P / 5|)$ for $C O O L$ action.
In all other conditions:
PV < (SP- $|S P / 3|)$ for HEAT action or $\mathrm{PV}>(S P+|S P / 3|)$ for COOL action.
6. What value will be returned by the device if a read query for the PV is sent and the device has Sensor/Over/Under range error?
A. Following values will be sent as reply for the modbus query to read temperature if device is in error mode.

| Error displyed | Value returned |
| :--- | :---: |
| SEnb (sensor open) | $0 \times \mathrm{C} 000$ |
| ovrg (over range error) | $0 \times \mathrm{C} 001$ |
| unrg (under range error) | $0 \times \mathrm{C} 002$ |

## 7.How to restart ramp and soak profile?

A. To restart the ramp soak profile program " C " key as "rsEt", then while on the main screen press and hold the key for about 2 s . When reset, the lower display alternates between a message "rsEt" and value configured on it by the user. This message disappears after a time of about 1 min.

| Menu | Sub menu | Options |
| :---: | :---: | :---: |
| conf | kEy | rSEt |

## 8. How to change Set point while on main Screen?

A. It is possible to change the set point while on main screen. For this set "kEy" parameter in "conF" menu as "chsP". Then any time when on main screen if the " C " key is pressed for more than 2 sec currently effective set point appears on the screen. The upper display start blinking. By using "UP" key or "DOWN" key the value can be changed. Press "E" key to save the value. To discard the value press " $C$ " key. To exit to main screen, press "C" key.

| Menu | Sub menu | Options |
| :---: | :---: | :---: |
| conf | kEy | chsp |

## 9. How to read SPLL value throught Modbus?

A. The query structure of read query is explained earlier. Assume that Salve address is 01 .

| Filed Name | Byte Position |
| :--- | :---: |
| Slave MODBUS ID | 0 |
| Function Code(3) | 03 |
| First Word Address MSB | 20 |
| First Word Address LSB | 01 |
| Number of words MSB | 04 |
| Number of words MSB | 01 |
| CRC MSB | $0 A$ |
| CRC LSB | DE |

## 10. Can we Autotune the device below ambient temperature in double acting mode?

A. Yes, but if SP > PV; then Auto tuning should be done only above ambient temperature. And if SP < PV, Autotuning should be done only below ambient temperature.

Ex 1.
If Auto tuning is desired for a Set Point of $60^{\circ} \mathrm{C}$ (i.e. $\mathrm{SP}=60$ ) \& device is configured in Dual Acting mode or Single Acting mode (Func = HEAT), then auto tuning will start only if $\mathrm{PV}<[60-|60 / 3|]=40^{\circ} \mathrm{C}$, if soft start is not configured.
Ex 2.
If Auto tuning is desired for a Set Point of $75^{\circ} \mathrm{C}$ (i.e. $\mathrm{SP}=75$ ) \& device is configured in Dual Acting mode or Single Acting mode(Func = HEAT), then auto tuning will start only if $\mathrm{PV}<[75-|75 / 5|]=60^{\circ} \mathrm{C}$, if soft start is configured.
11.How to see CJC tempareture in device?
A. Press "UP" and "DOWN" key simultaneously. CJC value will appear on lower display. To remove CJC value Press "EXIT" key. Device will show value for which lower display is configured.

## 12. How to reset device?

A. On main screen when you press the enter key, you will get the option for reset the device "rset". When you press the reset you will get option as "yes" or "No" to reset device. If press "Yes" you will get option to confirm the reset device. If again press "Yes" then device will be reset and back to main screen .
If press "No" after confirming to reset then you get back to main screen.

## 13.What happen if Sens, ourg, unrg or control action off condition occurs when timer is ON?

A. If the timer is started and any of the condition occurs then the timer time will get pause and resume again from the pause time when the condition vanish.

Note: For Cat_ID :151K42B only output 2 can be assign as Timer alarm (trAL).

## 25. Error Occurred in Device:

| Error | Error Details | Reason | Action |
| :---: | :---: | :---: | :---: |
| 5En5 | Sensor break error | Sensor is interrupted | Verify connection. between sensor and device \& then verify the correct functioning of the sensor |
| obrg | Over Range error | PV Value is above sensor limit |  |
| Uning | Under Range error | PV Value is under sensor limit |  |
| ErAt | Auto Tune error | Auto tunning cannot be started because process value is too high or too low | Press error key to make error disappear |
| noRt | Auto tunning time out | Auto tunning is not finished within 2 hrs |  |
| FRI L | Fail error | An attempt is made to change the auto tunning parameters during auto tunning |  |
| chri | Loop break interrupted | Loop control interrupted | Configure exit key to off \& make control output off |
| Err 1 | Memory error | Possibly EEPROM error | Press enter to make error disappear |
| 55r | SSR error | Possible SSR terminals are short | Check SSR terminals if error does not disappear after Enter key pressed |

## PASSWORD = 69

